## Metaheuristic Optimization <br> 18．Ant Colony Optimization

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## Outline

(1) Introduction
(2) Ant Colony Optimization

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## Clever Ants

- Research by Deneubourg et al. ${ }^{[1-3]}$ on real ants and the simulations by Stickland et al. ${ }^{[4]}$


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(5) Many combinatorial problems can be considered as finding the shortest path on a graph. Example: Traveling Salesman Problem
- Dorigo et al. ${ }^{[5]}$ have the idea to use a simulation of the way ants form a path in order to solve optimization problems which can be represented as graphs - Ant Colony Optimization (ACO)


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## Ant Path Finding

- ant nest (A) separated from food source (F) by obstacle


## (F)



## Ant Path Finding

- two ants (red and blue) leave the nest at the same time



## Ant Path Finding

- at the crossroad, one turns left and the other one right



## Ant Path Finding

- when moving, ants leave pheromone behind (dotted lines)



## Ant Path Finding

- the one with the shorter path arrives at the food source first



## Ant Path Finding

- when it turns back, it finds pheromone on one path and follows it



## Ant Path Finding

- by doing so, it leaves even more pheromone on the path



## Ant Path Finding

- now the second ant arrives at the food source



## Ant Path Finding

- when it turns back, there is pheromone on both paths - but more on the red one



## Ant Path Finding

- the pheromone on the short path gets more and more



## Ant Path Finding

- the pheromone on the short path gets more and more



## Ant Path Finding

- while the one on the blue path evaporates



## Ant Path Finding

- until only the short path has pheromone...



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- based on the objective value of the resulting paths, $\tau$ is updated


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- Knowledge about the problem may be incorporated as a heuristic $\eta$ which tells the ant how interesting a given edge is. Together with the pheromones, $\eta$ helps the ant to decide where to go. They don't change over time.


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p_{i, j}=\frac{\left(\tau_{i, j}\right)^{\alpha} *\left(\eta_{i, j}\right)^{\beta}}{\sum_{\forall k}\left(\tau_{i, k}\right)^{\alpha} *\left(\eta_{i, k}\right)} \tag{1}
\end{equation*}
$$

$p_{i, j} \quad$ probability of an ant to go to $j$ if at location $i$
$\alpha, \beta$ weight parameters
$\tau_{i, j} \quad$ amount of pheromone on the edge connecting $i$ and j
$\eta_{i, j} \quad$ visibility of node $j$ from $i$ : inversely proportional to distance between $j$ and $i$

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\tau_{i, j}=(1-\rho) \tau_{i, j}+\Delta \tau_{i, j} \tag{2}
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- $\rho$ is the evaporation coefficient (fraction of pheromone disappearing into thin air)
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- $\rho$ is the evaporation coefficient (fraction of pheromone disappearing into thin air)
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- the amount $\Delta \tau_{i, j}$ usually depends on the quality of the paths the edge $(i, j)$ was part of


## Example: Traveling Salesman Problem

A salesman wants to visit $n$ cities in the shortest possible time. No city should be visited twice and he wants arrive back at the origin by the end of the tour.


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\begin{aligned}
& \text { Minimize } f(x)= \sum_{i=0}^{4} \operatorname{dist}(x[i], x[i+1])+ \\
& \operatorname{dist}(x[4], x[0])
\end{aligned}
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- after all ants have completed their tour, pheromones are updated


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\sum_{k=1}^{p s} \begin{cases}\frac{1}{f\left(x_{k}\right)} & \text { if tour } x_{k} \text { contains edge } \overline{i j}  \tag{3}\\ 0 & \text { otherwise }\end{cases}
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Alternative method: only the best ant contributes to $\Delta \tau$

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(3) Update pheromone value $\tau_{i, j}$

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(3) Add the trip back to the starting node $\Longrightarrow$ We get tour $x_{k}$
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$$
\begin{equation*}
\tau_{i, j}=(1-\rho) \tau_{i, j}+\Delta \tau_{i, j} \tag{3}
\end{equation*}
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where the evaporation coefficient $\rho \in[0,1]$ lets old pheromone disappear

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- ACO: Copy ground-based movements / stigmergy


## 谢谢

## Thank you

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