





# Metaheuristic Optimization 6. Random Walk

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- The chance that a good solution is neighboring another good solution should be higher than that it is surrounded by only bad solutions or at a random location.
- Based on this idea, the hill climber generates modified copies of the current solution and accepts them if they are better than the old solution.
- What would happen if we would always accept them?



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#### $p_{best} \leftarrow randomWalk(f)$

**Input:** *f*: the objective function subject to minization **Input:** [implicit] shouldTerminate: the termination criterion **Data:** *p<sub>new</sub>*: the new solution to be tested **Output:** *p<sub>best</sub>*: the best individual ever discovered

### begin

```
\begin{array}{c} p_{best}.g \longleftarrow \text{create}() \\ p_{best}.x \longleftarrow \text{gpm}(p_{best}.g) \\ p_{best}.y \longleftarrow f(p_{best}.x) \\ p_{new} \longleftarrow p_{best} \\ \textbf{while} \neg should Terminate \ \textbf{do} \\ \left[\begin{array}{c} p_{new}.g \longleftarrow \text{mutation}(p_{new}.g) \\ p_{new}.x \leftarrow \text{gpm}(p_{new}.g) \\ p_{new}.y \leftarrow f(p_{new}.x) \\ \textbf{if} \ p_{new}.y \le p_{best}.y \ \textbf{then} \ p_{best} \leftarrow p_{new} \\ \textbf{return} \ p_{best} \end{array}\right]
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create initial candidate solution p<sub>best</sub> (also store it in p<sub>new</sub>)

- e derive new solution  $p_{new}$  from  $p_{new}$
- if  $p_{new}$  is better than  $p_{best}$ , set  $p_{best} = p_{new}$

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### begin

$$p_{best}.g \leftarrow create()$$

$$p_{best}.x \leftarrow gpm(p_{best}.g)$$

$$p_{best}.y \leftarrow f(p_{best}.x)$$

$$p_{new} \leftarrow p_{best}$$
while  $\neg shouldTerminate$  do
$$p_{new}.g \leftarrow mutation(p_{new}.g)$$

$$p_{new}.x \leftarrow gpm(p_{new}.g)$$

$$p_{new}.y \leftarrow f(p_{new}.x)$$
if  $p_{new}.y \leq p_{best}.y$  then  $p_{best} \leftarrow p_{new}$ 
return  $p_{best}$ 

create initial candidate solution p<sub>best</sub> (also store it in p<sub>new</sub>)

- e derive new solution  $p_{new}$  from  $p_{new}$
- if  $p_{new}$  is better than  $p_{best}$ , set  $p_{best} = p_{new}$
- go back to Ø, until termination criterion is met

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• Let us implement a random walk





Let us implement a random walk for
 numerical optimization (over R<sup>n</sup>) and for





- Let us implement a random walk for
  - igl( igl) numerical optimization (over  $\mathbb{R}^n)$  and for
  - e combinatorial optimization (e.g., for TSP over permutations).



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#### Listing: The Random Walk Algorithm

```
public class RandomWalk<G, X> extends OptimizationAlgorithm<G, X> {
  public Individual <G, X> solve(final IObjectiveFunction <X> f) {
    Individual <G, X> pstar, pnew;
    pstar = new Individual<>();
    pnew = new Individual <>();
    pstar.g = this.nullary.create(this.random);
    pstar.x = this.gpm.gpm(pstar.g);
    pstar.v = f.compute(pstar.x);
    pnew.assign(pstar):
    while (!(this.termination.shouldTerminate())) {
      pnew.g = this.unary.mutate(pnew.g, this.random);
      pnew.x = this.gpm.gpm(pnew.g);
      pnew.v = f.compute(pnew.x);
      if (pnew.v <= pstar.v) {
        pstar.assign(pnew);
      3
    return pstar;
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```



• Now we have: first simple metaheuristic algorithm



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- Is it good?



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- Is it good?
- When is optimization efficient?



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- Now we have: first simple metaheuristic algorithm
- Is it good?
- When is optimization efficient?
- When the information we get, e.g., from objective function evaluation, is used efficiently
- Comparison with algorithms that do not use this information!



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- Hence, their performance is much worse, similar to random sampling.
- This means that the idea of expection some sort of "gradient" in the search space towards better solutions is reasonable.





谢谢 Thank you

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